

Robotic neurosurgery systems

see <https://moffitt.org/media/4327/352.pdf>

Technically, surgical robots can be divided into passive or active systems. A passive system is one in which the surgeon provides the physical energy to drive the surgical tool ¹⁾.

Some commonly used robots available for neurosurgery are the [neuromate](#) (Renishaw Mayfield, Lyon, France), [Pathfinder](#) (Prosurgics, High Wycombe, United Kingdom), the [NeuroArm](#) (University of Calgary, Calgary, Alberta, Canada), the [SpineAssist](#) (MAZOR Robotics, Orlando, Florida), and [Renaissance](#) (MAZOR Robotics).

[Da Vinci robot](#)

[MARS](#)

[Mazor robotics](#)

[Neuromate](#) stereotactic robot (Renishaw, Gloucestershire, UK)

[PUMA 200](#)

[Rosa](#)

[Stealth Autoguide](#)

see [Robotic Stereotaxy systems](#).

¹⁾

Mckay-Davies I, Bann S, Darzi A. Robotics in surgery. Student BMJ. 2002;10:215-258.

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