

# Image-guided stereotactic surgery

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A method in neurosurgery for locating points within the brain using an external, three-dimensional frame of reference usually based on the [Cartesian coordinate system](#).

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The term [stereotactic](#) (Greek: stereo = 3-dimensional, tactic = to touch) surgery was initially used in [animals](#), and was based on [atlases](#) of three-dimensional coordinates compiled from [dissections](#). The term was then used for surgery performed in humans, usually for [thalamic](#) lesioning to treat [Parkinsonism](#).

The [techniques](#) of [stereotactic surgery](#) are utilized in some functional procedures (e.g. [DBS](#)) as well as for biopsies (see [Stereotactic biopsy](#)) [cyst](#) drainage, etc. The term [stereotactic](#) (Greek: stereo = 3-dimensional, tactic = to touch) surgery was initially used in animals, and was based on atlases of three-dimensional coordinates compiled from dissections. The term was then used for surgery performed in humans, usually for [thalamic](#) lesioning to treat [Parkinsonism](#), see [Parkinson's disease surgery](#), where the target site to be lesioned was located relative to [landmarks](#) with intraoperative [pneumoencephalography](#) or contrast [ventriculography](#). Use of this procedure fell off dramatically in the late [1960s](#) with the introduction of [L-dopa](#) for [Parkinsonism](#) <sup>1)</sup>

## Indications

see [Stereotactic surgery indications](#).

For image-guided [stereotactic surgery](#), in the first part of the procedure, a [CT](#) scan or [MRI](#) (or occasionally, [angiogram](#)) is performed. For increased precision, “[fiducial](#)” markers or a [stereotactic frame](#) is attached to the patient’s head during this image acquisition phase. Acceptable accuracy for [biopsy](#) can often be obtained using high resolution thin cut imaging slices (usually with a 0 angle of the [gantry](#)), and then surface matching algorithms in the guidance system will match the pre-op CT/MRI to the patient’s head. This is not accurate enough for lesion generation or [electrode placement](#). The second part of the procedure usually takes place in an [operating room](#). The patient is “registered” with the pre-op images, and then tracking cameras follow the movement of instruments with appropriate attachments to show in “real-time” the location of the instrument with respect to the pre-op image. An important limitation to be aware of is the fact that the pre-op images are “historical”

and are not updated as the surgical procedure alters the anatomy of the patient. Even the administration of [mannitol](#) can cause brain shifts that may cause the target of the surgery to move away from its pre-op location by several millimeters <sup>2)</sup>.

<sup>1)</sup>

Gildenberg PL. Whatever Happened to Stereotactic Surgery? Neurosurgery. 1987; 20:983-987

<sup>2)</sup>

Bucholz RD, Yeh DD, Trobaugh J, et al. The correction of stereotactic inaccuracy caused by brain shift using an intraoperative ultrasound device. In: Lecture Notes in Computer Science. Berlin: Springer; 1997. DOI: 10.1007/BFb0029268

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